

Pressure is force per unit area, $d\vec{F} = -pd\vec{A}$, where the direction of \vec{A} is outward along the surface normal.

The compressibility of a fluid $k = -(1/V)\partial V/\partial p$. $k = 1/p$ for an ideal gas, but is much smaller for ordinary liquids, which can be regarded as approximately incompressible ($k \approx 0$).

Pressure variation in a column of incompressible liquid $p(z) = p_0 + \rho g(h - z)$ where h is the height of the column. The gradient of the pressure gives the *force per unit volume* $\vec{f} = -\nabla p$. The volume integral of $\int_V \vec{f} dV$ is the hydrostatic force on the material in the enclosed volume.

Pascal's principle: An external pressure is transmitted undiminished to all parts of a fluid in equilibrium. Note that this is a statement about the pressure, not the force.

Archimedes principle: The bouyant force on an object in a fluid is the weight of the excluded fluid.

Force on curved surface: The force from a fluid with (constant) pressure p on a hemisphere of radius R is $\vec{F} = \oint_S pd\vec{A} = \pi pR^2$. In general, if the pressure is constant, this force depends only on the cross sectional area perpendicular to the line of action of the force.

Divergence Theorem: For any vector field $\vec{u}(\vec{r})$, the flux of \vec{u} through a closed surface \mathcal{S} is $\oint_S \vec{u} \cdot d\vec{A} = \int_V \vec{\nabla} \cdot \vec{u} dV$. This means the total flow of \vec{u} through the closed surface is the sum of the net flows from each point (aka the *divergence* of \vec{u}) contained in the volume bounded by the surface. (Worked example: a calculation of the Archimedes force from the pressure of a fluid at the boundary of an immersed object).

Surface Tension: The surface energy of a fluid is $U_s = \gamma A$ where A is the surface area and γ is the surface tension. $[\gamma] = \text{J/m}^2 = \text{N/m}$. The latter is useful for formulating the surface tension force using the contact "line".

Equation of Continuity: For a steady flow bounded by a container of varying cross sectional area A , the volume flow rate $\Phi = vA$ is constant.

Equation of Motion: The force density $\vec{f} = \rho\partial\vec{v}/\partial t + \rho(\vec{v} \cdot \vec{\nabla})\vec{v}$, where the second term is called the "convective derivative." For steady flow we have $\vec{f} = \rho(\vec{v} \cdot \vec{\nabla})\vec{v}$. In these expressions \vec{v} is the average velocity of all the particles found in a fixed volume element of the fluid.

Note: for steady flow in a circular channel $(\vec{v} \cdot \vec{\nabla})\vec{v} = -(v^2/r)\hat{r}$ in each volume element. This gives the net "centripetal acceleration" of the particles in the volume element. Since the flow is steady $\partial\vec{v}/\partial t = 0$.

Bernoulli's Law: For steady, incompressible and irrotational flow, $(1/2)\rho v^2 + \rho g z + p = \text{constant}$. This is the work energy theorem for steady flow in a fluid.

Torricelli's Law: The flow velocity from a liquid column of height h is the free fall velocity $v = \sqrt{2gh}$.

The viscous force transmitted across a surface \mathcal{A} of a flowing liquid is $F/\mathcal{A} = \eta\dot{\epsilon}$ where $\dot{\epsilon}$ is the strain rate and η is the viscosity.

Poiseuille's Law: The flow velocity of a viscous fluid in a circular pipe with radius R and length ℓ is *nonuniform*

$$v(r) = \frac{\Delta p}{4\eta\ell} (R^2 - r^2) \quad (1)$$

and the volume flow rate is proportional to R^4

$$\Phi = \frac{\pi R^4 \Delta p}{8\eta\ell} \quad (2)$$

Stokes' Law: A sphere of radius R moving at velocity v relative to a fluid with viscosity η experiences a viscous drag force $F_v = 6\pi\eta Rv$.

The pressure from a gas on the walls of its container is calculated from kinetic theory $p = 2n\langle K \rangle/3$ where n is the number of particles per unit volume and $\langle K \rangle$ is the mean kinetic (translational) kinetic energy. This gives a microscopic basis for the ideal gas equation of state $p\mathcal{V} = NkT = N_m\mathcal{R}T$ where k is Boltzmann's constant, and \mathcal{R} is the gas constant.

Two Equilibria: Mechanical equilibrium between two otherwise isolated systems that are free to exchange volumes is established when the pressures are equal. Thermal equilibrium between two systems that can exchange energy is established when the temperatures are equal.

Heat I: When two otherwise isolated systems at different temperatures are in thermal contact, heat flows from the high temperature to low temperature system. This is a nonequilibrium state. Warning: do not confuse temperature and heat.

Heat II: The heat capacity of an object is the ratio of the heat required to raise the temperature by ΔT to the temperature change, $C = Q/\Delta T$ in the limit that $\Delta T \rightarrow 0$. The heat capacity is an extensive quantity that is proportional to the total number of particles in the system. It is useful to re-express this as a specific heat $c = C/N$ or a molar heat capacity $c^m = C/N_m$. For compressible states (like a gas) we need to specify the thermodynamic state of the system while the heat is added, by distinguishing between the specific heats at constant volume and at constant pressure.

Specific Heats for Ideal Gases For a monatomic ideal gas, only the translational motions contribute to the thermal energy so that the molar heat capacity $c_v^m = 3R/2$ where R is the universal gas constant. By the equipartition theorem each "thermally accessible" degree of freedom contributes $kT/2$ to the internal energy so that, for example, an ideal diatomic gas has a molar heat capacity $c_v^m = 5R/2$. In general the heat capacity can depend on the temperature since at high temperature more internal motions become thermally accessible.

Heat III: The rate of flow of heat \dot{Q} through a rectangular parallelepiped of cross sectional area \mathcal{A} and width d is

$$\dot{Q} = \frac{k\mathcal{A}\Delta T}{d} \quad (3)$$

where k is the thermal conductivity, and ΔT is the temperature difference across the width of the parallelepiped.